APCH procedure coding of ILS Z RWY 28

1. ILS Z RWY 28: INITIAL APPROACH SEGMENT FROM PQ228

RCMD.PATH TEMINATOR	FIX ID (WPT NAME)	FLY-OVER	DISTANCE (KM)	MAG TRACK (TRUE TRACK)	TURN DIRECTION	ALTITUDE (M)	SPEED LIMIT (IAS) KM/H	VER ANGLE	NAV PER
IF	PQ228	-	-	-	-	1200	-	-	RNP 1
TF	PQ128	-	10.4	285 (284.5)	-	800	-	-	RNP 1

2. ILS Z RWY 28: INITIAL APPROACH SEGMENT FROM PQ328

RCMD.PATH TEMINATOR	FIX ID (WPT NAME)	FLY-OVER	DISTANCE (KM)	MAG TRACK (TRUE TRACK)	TURN DIRECTION	ALTITUDE (M)	SPEED LIMIT (IAS) KM/H	VER ANGLE	NAV PER
IF	PQ328	-	-	-	-	1500	-	-	RNP 1
TF	PQ128	-	13.0	186 (185.7)	-	800	-	-	RNP 1

3. ILS Z RWY 28: INITIAL APPROACH SEGMENT FROM PQ428

RCMD.PATH TEMINATOR	FIX ID (WPT NAME)	FLY-OVER	DISTANCE (KM)	MAG TRACK (TRUE TRACK)	TURN DIRECTION	ALTITUDE (M)	SPEED LIMIT (IAS) KM/H	VER ANGLE	NAV PER
IF	PQ428	-	-	-	-	1500	-	-	RNP 1
TF	PQ128	-	13.0	006 (005.7)	-	800	-	-	RNP 1

4. ILS Z RWY 28: MISSED APPROACH SEGMENT

RCMD.PATH TEMINATOR	FIX ID (WPT NAME)	FLY-OVER	DISTANCE (KM)	MAG TRACK (TRUE TRACK)	TURN DIRECTION	ALTITUDE (M)	SPEED LIMIT (IAS) KM/H	VER ANGLE	NAV PER
IF	MAPT	Y	-	-	-	-	-	-	RNP 1
DF	PQ600	Y	-	-	-	-	-	-	RNP 1
TF	PQ601	-	33.6	219 (218.8)	L	900	-	-	RNP 1
HM	PQ601	Y	-	077 (076.1)	R	-1200 +900	-	-	RNP 1

5. HOLDING PROCEDURE

Holding Fix	Fly-over	Inbound Course/ Track °M(°T)	Magnetic Variation	Time (min)	Turn Direction	Altitude (m)	Speed (km/h)	Nav Spec
PQ601	Y	077 (076.1)	+0.4	1 ≤ FL140	R	-1200 +900	-430 ≤ FL140	RNP 1
PQ228	Y	285 (284.5)	+0.4	1 ≤ FL140 1.5 > FL140	R	+1200	-430 ≤ FL140 -445 > FL140	RNP 1
PQ328	Y	186 (185.7)	+0.4	1 ≤ FL140 1.5 > FL140	L	+1500	-430 ≤ FL140 -445 > FL140	RNP 1
PQ428	Y	006 (005.7)	+0.4	1 ≤ FL140 1.5 > FL140	R	+1500	-430 ≤ FL140 -445 > FL140	RNP 1